

4.2.1 The operators are (I have included  $\hbar$ , but OK if not there)

$$L_x \doteq \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad L_y \doteq \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix} \quad L_z \doteq \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

(1) Possible values of  $L_z$  must be eigenvalues.  $L_z$  is already diagonal, so eigenvalues can be read off by inspection:

$$L_z = \hbar, 0, -\hbar \quad (\text{or } 1, 0, -1)$$

(2) Initial state is  $|\psi\rangle = |L_z = \hbar\rangle \doteq \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ . Find expectation values:

$$\langle L_x \rangle = \langle \psi | L_x | \psi \rangle = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = 0$$

$$\begin{aligned} \langle L_x^2 \rangle &= \langle \psi | L_x^2 | \psi \rangle = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \\ &= \frac{\hbar^2}{2} \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \frac{\hbar^2}{2} \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = \frac{\hbar^2}{2} \end{aligned}$$

The uncertainty is

$$\Delta L_x = \sqrt{\langle L_x^2 \rangle - \langle L_x \rangle^2} = \sqrt{\frac{\hbar^2}{2} - 0} = \frac{\hbar}{\sqrt{2}}$$

(3) For  $L_x$  the diagonalization yields the eigenvalues

$$\begin{aligned} L_x &\doteq \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \\ \begin{pmatrix} -\lambda & \frac{\hbar}{\sqrt{2}} & 0 \\ \frac{\hbar}{\sqrt{2}} & -\lambda & \frac{\hbar}{\sqrt{2}} \\ 0 & \frac{\hbar}{\sqrt{2}} & -\lambda \end{pmatrix} &= 0 \Rightarrow -\lambda \left( \lambda^2 - \frac{\hbar^2}{2} \right) - \frac{\hbar}{\sqrt{2}} \left( -\lambda \frac{\hbar}{\sqrt{2}} \right) = 0 \\ \lambda (\lambda^2 - \hbar^2) &= 0 \Rightarrow \lambda = 1\hbar, 0, -1\hbar \end{aligned}$$

and the eigenvectors

$$\frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \hbar \begin{pmatrix} a \\ b \\ c \end{pmatrix} \Rightarrow \begin{aligned} b &= a\sqrt{2} \\ a+c &= b\sqrt{2} \\ b &= c\sqrt{2} \end{aligned}$$

$$|a|^2 + |b|^2 + |c|^2 = 1 \Rightarrow |b|^2 \left(\frac{1}{2} + 1 + \frac{1}{2}\right) = 1 \Rightarrow b = \frac{1}{\sqrt{2}}, a = \frac{1}{2}, c = \frac{1}{2}$$

$$|1\rangle_x = \frac{1}{2}|1\rangle + \frac{1}{\sqrt{2}}|0\rangle + \frac{1}{2}|-1\rangle$$

$$\frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0\hbar \begin{pmatrix} a \\ b \\ c \end{pmatrix} \Rightarrow \begin{aligned} b &= 0 \\ a+c &= 0 \\ b &= 0 \end{aligned}$$

$$|a|^2 + |b|^2 + |c|^2 = 1 \Rightarrow |a|^2(1+1) = 1 \Rightarrow a = \frac{1}{\sqrt{2}}, b = 0, c = -\frac{1}{\sqrt{2}}$$

$$|0\rangle_x = \frac{1}{\sqrt{2}}|1\rangle - \frac{1}{\sqrt{2}}|-1\rangle$$

$$\frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = -\hbar \begin{pmatrix} a \\ b \\ c \end{pmatrix} \Rightarrow \begin{aligned} b &= -a\sqrt{2} \\ a+c &= -b\sqrt{2} \\ b &= -c\sqrt{2} \end{aligned}$$

$$|a|^2 + |b|^2 + |c|^2 = 1 \Rightarrow |b|^2 \left(\frac{1}{2} + 1 + \frac{1}{2}\right) = 1 \Rightarrow b = -\frac{1}{\sqrt{2}}, a = \frac{1}{2}, c = \frac{1}{2}$$

$$|-1\rangle_x = \frac{1}{2}|1\rangle - \frac{1}{\sqrt{2}}|0\rangle + \frac{1}{2}|-1\rangle$$

(4) Initial state is  $|\psi\rangle = |L_z = -\hbar\rangle \doteq \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ . Possible results of  $L_x$  measurement are eigenvalues

of  $L_x$ :  $L_x = \hbar, 0, -\hbar$  (or  $1, 0, -1$ ). The probabilities are

$$\mathcal{P}_{1x} = \left| \langle 1 | \psi \rangle \right|^2 = \left| \left( \frac{1}{2} \langle 1 | + \frac{1}{\sqrt{2}} \langle 0 | + \frac{1}{2} \langle -1 | \right) (|-1\rangle) \right|^2 = \left| \frac{1}{2} \right|^2 = \frac{1}{4}$$

$$\mathcal{P}_{0x} = \left| \langle 0 | \psi \rangle \right|^2 = \left| \left( \frac{1}{\sqrt{2}} \langle 1 | - \frac{1}{\sqrt{2}} \langle -1 | \right) (|-1\rangle) \right|^2 = \left| -\frac{1}{\sqrt{2}} \right|^2 = \frac{1}{2}$$

$$\mathcal{P}_{-1x} = \left| \langle -1 | \psi \rangle \right|^2 = \left| \left( \frac{1}{2} \langle 1 | - \frac{1}{\sqrt{2}} \langle 0 | + \frac{1}{2} \langle -1 | \right) (|-1\rangle) \right|^2 = \left| \frac{1}{2} \right|^2 = \frac{1}{4}$$

The three probabilities add to unity, as they must.

(5) Initial state is  $|\psi_{in}\rangle \doteq \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$ . Possible results of  $L_z^2$  measurement are eigenvalues of  $L_z^2$ .

$L_z^2$  is already diagonal:

$$L_z^2 \doteq \hbar^2 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

so eigenvalues can be read off by inspection:

$$L_z^2 = \hbar^2, 0, \hbar^2 \quad (\text{or } 1, 0, 1)$$

Note the degeneracy: the states  $|1\rangle$  and  $|-1\rangle$  produce the same eigenvalue  $\hbar^2$ . Hence we must use the projection operator to find the state after a measurement that yields  $\hbar^2$ :

$$|\psi_{out}\rangle = \frac{P_{\hbar^2} |\psi_{in}\rangle}{\sqrt{\langle \psi_{in} | P_{\hbar^2} | \psi_{in} \rangle}}$$

For this case, we get

$$\begin{aligned} |\psi_{out}\rangle &= \frac{(P_1 + P_{-1}) |\psi_{in}\rangle}{\sqrt{\langle \psi_{in} | (P_1 + P_{-1}) | \psi_{in} \rangle}} = \frac{(|1\rangle\langle 1| + |-1\rangle\langle -1|) |\psi_{in}\rangle}{\sqrt{\langle \psi_{in} | (|1\rangle\langle 1| + |-1\rangle\langle -1|) | \psi_{in} \rangle}} \\ &= \frac{(|1\rangle\langle 1| + |-1\rangle\langle -1|) |\psi_{in}\rangle}{\sqrt{\langle \psi_{in} | (|1\rangle\langle 1| + |-1\rangle\langle -1|) | \psi_{in} \rangle}} \\ &= \frac{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{\sqrt{2}} \end{pmatrix}}{\sqrt{\langle \psi_{in} | (|1\rangle\langle 1| + |-1\rangle\langle -1|) | \psi_{in} \rangle}} = \begin{pmatrix} \frac{1}{2} \\ 0 \\ \frac{1}{\sqrt{2}} \end{pmatrix} \\ &= \frac{\begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \frac{1}{2} \\ 0 \\ \frac{1}{\sqrt{2}} \end{pmatrix}}{\sqrt{\langle \psi_{in} | (|1\rangle\langle 1| + |-1\rangle\langle -1|) | \psi_{in} \rangle}} = \frac{3}{4} \\ &= \frac{2}{\sqrt{3}} \begin{pmatrix} \frac{1}{2} \\ 0 \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{\sqrt{2}}{\sqrt{3}} \end{pmatrix} \end{aligned}$$

The probability is given by the expectation value of the projection, which is included in the above calculation

$$\mathcal{P}_{L_z^2=\hbar^2} = \langle \psi_{in} | (P_1 + P_{-1}) | \psi_{in} \rangle = \langle \psi_{in} | (|1\rangle\langle 1| + |-1\rangle\langle -1|) | \psi_{in} \rangle = \frac{3}{4}$$

If we now measure  $L_z$ , then the possible results are the eigenvalues of  $L_z$ :  $L_z = \hbar, 0, -\hbar$  (or 1, 0, -1). The probabilities are

$$\mathcal{P}_1 = |\langle 1 | \psi_{out} \rangle|^2 = \left| \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{\sqrt{2}}{\sqrt{3}} \end{pmatrix} \right|^2 = \frac{1}{3}$$

$$\mathcal{P}_0 = |\langle 0 | \psi_{out} \rangle|^2 = \left| \begin{pmatrix} 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{\sqrt{2}}{\sqrt{3}} \end{pmatrix} \right|^2 = 0$$

$$\mathcal{P}_{-1} = |\langle -1 | \psi_{out} \rangle|^2 = \left| \begin{pmatrix} 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{3}} \\ 0 \\ \frac{\sqrt{2}}{\sqrt{3}} \end{pmatrix} \right|^2 = \frac{2}{3}$$

(6) If we know that

$$\mathcal{P}_1 = |\langle 1 | \psi_{out} \rangle|^2 = \frac{1}{4}$$

$$\mathcal{P}_0 = |\langle 0 | \psi_{out} \rangle|^2 = \frac{1}{2}$$

$$\mathcal{P}_{-1} = |\langle -1 | \psi_{out} \rangle|^2 = \frac{1}{4}$$

Then we can solve these to find that

$$\langle 1 | \psi_{out} \rangle = \frac{1}{2} e^{i\delta_1}$$

$$\langle 0 | \psi_{out} \rangle = \frac{1}{\sqrt{2}} e^{i\delta_2}$$

$$\langle -1 | \psi_{out} \rangle = \frac{1}{2} e^{i\delta_3}$$

noting that answers can be complex. Thus the initial state must be

$$|\psi_{in}\rangle = \frac{1}{2} e^{i\delta_1} |1\rangle + \frac{1}{\sqrt{2}} e^{i\delta_2} |0\rangle + \frac{1}{2} e^{i\delta_3} |-1\rangle$$

An overall phase is not physically measurable, but relative phases are. For example, if we calculate

$$\begin{aligned} \mathcal{P}_{1,x} &= \left| \langle 1 | \psi_{in} \rangle \right|^2 = \left| \left( \frac{1}{2} \langle 1 | + \frac{1}{\sqrt{2}} \langle 0 | + \frac{1}{2} \langle -1 | \right) \left( \frac{1}{2} e^{i\delta_1} |1\rangle + \frac{1}{\sqrt{2}} e^{i\delta_2} |0\rangle + \frac{1}{2} e^{i\delta_3} |-1\rangle \right) \right|^2 \\ &= \left| \left( \frac{1}{4} e^{i\delta_1} + \frac{1}{2} e^{i\delta_2} + \frac{1}{4} e^{i\delta_3} \right) \right|^2 = \left| e^{i\delta_1} \left( \frac{1}{4} + \frac{1}{2} e^{i(\delta_2 - \delta_1)} + \frac{1}{4} e^{i(\delta_3 - \delta_1)} \right) \right|^2 \\ &= \left( \frac{1}{4} + \frac{1}{2} e^{-i(\delta_2 - \delta_1)} + \frac{1}{4} e^{-i(\delta_3 - \delta_1)} \right) \left( \frac{1}{4} + \frac{1}{2} e^{i(\delta_2 - \delta_1)} + \frac{1}{4} e^{i(\delta_3 - \delta_1)} \right) \\ &= \frac{1}{16} + \frac{1}{4} + \frac{1}{16} + \frac{1}{4} \cos(\delta_2 - \delta_1) + \frac{1}{8} \cos(\delta_3 - \delta_1) + \frac{1}{4} \cos(\delta_3 - \delta_2) \end{aligned}$$

we can rewrite this in terms of two phases:

$$\begin{aligned}\phi_1 &= \delta_2 - \delta_1 \\ \phi_2 &= \delta_3 - \delta_1 \\ \mathcal{P}_{1x} &= \frac{1}{16} + \frac{1}{4} + \frac{1}{16} + \frac{1}{4} \cos \phi_1 + \frac{1}{8} \cos \phi_2 + \frac{1}{4} \cos(\phi_2 - \phi_1)\end{aligned}$$

so we can safely set one phase to zero and write

$$|\psi_{in}\rangle = \frac{1}{2}|1\rangle + \frac{1}{\sqrt{2}}e^{i\phi_1}|0\rangle + \frac{1}{2}e^{i\phi_2}|-1\rangle$$

2.23 (a) The commutator is

$$\begin{aligned}[A, B] &= AB - BA \doteq \begin{pmatrix} a_1 & 0 & 0 \\ 0 & a_2 & 0 \\ 0 & 0 & a_3 \end{pmatrix} \begin{pmatrix} b_1 & 0 & 0 \\ 0 & 0 & b_2 \\ 0 & b_2 & 0 \end{pmatrix} - \begin{pmatrix} b_1 & 0 & 0 \\ 0 & 0 & b_2 \\ 0 & b_2 & 0 \end{pmatrix} \begin{pmatrix} a_1 & 0 & 0 \\ 0 & a_2 & 0 \\ 0 & 0 & a_3 \end{pmatrix} \\ &\doteq \begin{pmatrix} a_1 b_1 & 0 & 0 \\ 0 & 0 & a_2 b_2 \\ 0 & a_3 b_2 & 0 \end{pmatrix} - \begin{pmatrix} a_1 b_1 & 0 & 0 \\ 0 & 0 & a_3 b_2 \\ 0 & a_2 b_2 & 0 \end{pmatrix} \\ &\doteq \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & b_2(a_2 - a_3) \\ 0 & b_2(a_3 - a_2) & 0 \end{pmatrix} \neq 0\end{aligned}$$

so they do not commute.

(b)  $A$  is already diagonal, so the eigenvalues and eigenvectors are obtained by inspection. The eigenvalues are

$$a_1, a_2, a_3$$

and the eigenvectors are

$$|a_1\rangle = |1\rangle \doteq \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad |a_2\rangle = |2\rangle \doteq \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad |a_3\rangle = |3\rangle \doteq \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

For  $B$ , diagonalization yields the eigenvalues

$$\begin{aligned}\begin{pmatrix} b_1 - \lambda & 0 & 0 \\ 0 & -\lambda & b_2 \\ 0 & b_2 & -\lambda \end{pmatrix} = 0 &\Rightarrow (b_1 - \lambda)(\lambda^2 - b_2^2) = 0 \\ \Rightarrow \lambda &= b_1, b_2, -b_2\end{aligned}$$

and the eigenvectors

$$\begin{pmatrix} b_1 & 0 & 0 \\ 0 & 0 & b_2 \\ 0 & b_2 & 0 \end{pmatrix} \begin{pmatrix} u \\ v \\ w \end{pmatrix} = b_1 \begin{pmatrix} u \\ v \\ w \end{pmatrix} \Rightarrow \begin{aligned} b_1 u &= b_1 u \\ b_2 w &= b_1 v \Rightarrow w = v = 0 \\ b_2 v &= b_1 w \end{aligned}$$

$$|u|^2 + |v|^2 + |w|^2 = 1 \Rightarrow |u|^2 = 1 \Rightarrow u = 1, v = 0, w = 0 \Rightarrow |b_1\rangle = |1\rangle \doteq \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} b_1 & 0 & 0 \\ 0 & 0 & b_2 \\ 0 & b_2 & 0 \end{pmatrix} \begin{pmatrix} u \\ v \\ w \end{pmatrix} = b_2 \begin{pmatrix} u \\ v \\ w \end{pmatrix} \Rightarrow \begin{aligned} b_1 u &= b_2 u \\ b_2 w &= b_2 v \Rightarrow u = 0, w = v \\ b_2 v &= b_2 w \end{aligned}$$

$$\langle b_2 | b_2 \rangle = 1 \Rightarrow |v|^2 + |w|^2 = 1 \Rightarrow u = 0, v = \frac{1}{\sqrt{2}}, w = \frac{1}{\sqrt{2}} \Rightarrow |b_2\rangle = \frac{1}{\sqrt{2}}(|2\rangle + |3\rangle) \doteq \begin{pmatrix} 0 \\ \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$$

$$\begin{pmatrix} b_1 & 0 & 0 \\ 0 & 0 & b_2 \\ 0 & b_2 & 0 \end{pmatrix} \begin{pmatrix} u \\ v \\ w \end{pmatrix} = -b_2 \begin{pmatrix} u \\ v \\ w \end{pmatrix} \Rightarrow \begin{aligned} b_1 u &= -b_2 u \\ b_2 w &= -b_2 v \Rightarrow u = 0, w = -v \\ b_2 v &= -b_2 w \end{aligned}$$

$$\langle -b_2 | -b_2 \rangle = 1 \Rightarrow |v|^2 + |w|^2 = 1 \Rightarrow u = 0, v = \frac{1}{\sqrt{2}}, w = -\frac{1}{\sqrt{2}} \Rightarrow |-b_2\rangle = \frac{1}{\sqrt{2}}(|2\rangle - |3\rangle) \doteq \begin{pmatrix} 0 \\ \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix}$$

c) If  $B$  is measured, the possible results are the allowed eigenvalues  $b_1, b_2, -b_2$ . If the initial state is  $|\psi_i\rangle = |2\rangle$ , then the probabilities are

$$\mathcal{P}_{b_1} = |\langle b_1 | \psi_i \rangle|^2 = |\langle 1 | 2 \rangle|^2 = 0$$

$$\mathcal{P}_{b_2} = |\langle b_2 | \psi_i \rangle|^2 = \left| \frac{1}{\sqrt{2}} (\langle 2 | + \langle 3 |) | 2 \rangle \right|^2 = \frac{1}{2}$$

$$\mathcal{P}_{-b_2} = |\langle -b_2 | \psi_i \rangle|^2 = \left| \frac{1}{\sqrt{2}} (\langle 2 | - \langle 3 |) | 2 \rangle \right|^2 = \frac{1}{2}$$

If  $A$  is then measured, the possible results are the allowed eigenvalues  $a_1, a_2, a_3$ . If  $b_2$  was the first result, then the new state is  $|b_2\rangle$  and when  $A$  is measured the subsequent probabilities are

$$\mathcal{P}_{a_1} = |\langle a_1 | b_2 \rangle|^2 = \left| \langle 1 | \frac{1}{\sqrt{2}}(|2\rangle + |3\rangle) \rangle \right|^2 = 0$$

$$\mathcal{P}_{a_2} = |\langle a_2 | b_2 \rangle|^2 = \left| \langle 2 | \frac{1}{\sqrt{2}}(|2\rangle + |3\rangle) \rangle \right|^2 = \frac{1}{2}$$

$$\mathcal{P}_{a_3} = |\langle a_3 | b_2 \rangle|^2 = \left| \langle 3 | \frac{1}{\sqrt{2}}(|2\rangle + |3\rangle) \rangle \right|^2 = \frac{1}{2}$$

If  $-b_2$  was the first result, then the new state is  $|-b_2\rangle$  and when  $A$  is measured the subsequent probabilities are

$$\mathcal{P}_{a_1} = |\langle a_1 | -b_2 \rangle|^2 = \left| \langle 1 | \frac{1}{\sqrt{2}}(|2\rangle - |3\rangle) \rangle \right|^2 = 0$$

$$\mathcal{P}_{a_2} = |\langle a_2 | -b_2 \rangle|^2 = \left| \langle 2 | \frac{1}{\sqrt{2}}(|2\rangle - |3\rangle) \rangle \right|^2 = \frac{1}{2}$$

$$\mathcal{P}_{a_3} = |\langle a_3 | -b_2 \rangle|^2 = \left| \langle 3 | \frac{1}{\sqrt{2}}(|2\rangle - |3\rangle) \rangle \right|^2 = \frac{1}{2}$$

d) If two operators do not commute, then the corresponding observables cannot be measured simultaneously. Part (a) tells us that the operators  $A$  and  $B$  not commute. Part (c) tells us that measurement  $B$  "disturbs" the measurement of  $A$  so the two measurements are not compatible (cannot be made simultaneously). So even though we started in state  $|\psi_i\rangle = |2\rangle$ , which is an eigenstate of  $A$  (meaning we know that the system has  $A = a_2$ ), the measurement of  $B$  puts the system into a state for which  $A$  is now not well defined, as evidenced by the subsequent  $A$  measurement.