

PH 211 - Chapter 10 Homework Solutions

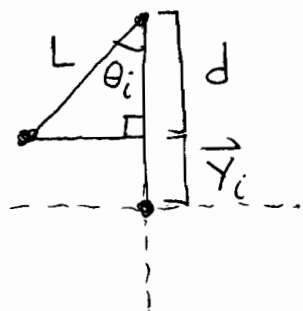
7) $m_o = 4m_H$ $K_o = K_H$ $v_H/v_o = ?$

$$\frac{K_H}{K_o} = \frac{\frac{1}{2} m_H v_H^2}{\frac{1}{2} m_o v_o^2} = \frac{m_H v_H^2}{m_o v_o^2} = 1 \quad \frac{v_H}{v_o} = \sqrt{\frac{m_o}{m_H}} = \sqrt{\frac{4m_H}{m_H}} = 2.00$$

11) $m = 500 \text{ g} = 0.500 \text{ kg}$

$L = 0.750 \text{ m}$ $\theta_i = 30.0^\circ$ $v_i = 0$

(a)



$$\vec{Y}_f = 0 \quad \cos \theta_i = \frac{\text{adj}}{\text{hyp}} = \frac{d}{L}$$

$$d = L \cos \theta_i \quad d + \vec{Y}_i = L$$

$$\vec{Y}_i = L - d = L - L \cos \theta_i$$

$$\vec{Y}_i = L(1 - \cos \theta_i)$$

$$K_i + U_{g_i} = K_f + U_{g_f} \quad 0 + mg\vec{Y}_i = \frac{1}{2} m v_f^2 + 0$$

$$v_f = \sqrt{2g\vec{Y}_i} = \sqrt{2gL(1 - \cos \theta_i)} = (2(9.80)(0.750)(1 - \sqrt{3}/2))^{1/2}$$

$$v_f = 1.40 \text{ m/s}$$

(b) $\theta_f = \theta_i = 30.0^\circ$ due to symmetry

34) $v_i = 80.0 \text{ m/s}$

$$\vec{Y}_i = +10.0 \text{ m}$$

$$v_f = ?$$

$$\vec{Y}_f = 0$$

$$K_i + U_{g_i} = K_f + U_{g_f}$$

$$\frac{1}{2} m v_i^2 + mg\vec{Y}_i = \frac{1}{2} m v_f^2 + 0$$

$$v_f = \sqrt{v_i^2 + 2g\vec{Y}_i} = ((80.0)^2 + 2(9.80)(10.0))^{1/2} = 81.2 \text{ m/s}$$

35) (a) No, because the gravitational potential energy and kinetic energy do not depend on the angle or direction.

$$(b) K_i + U_{g_i} = K_f + U_{g_f} \quad \frac{1}{2} m v_i^2 + mg\vec{Y}_i = \frac{1}{2} m v_f^2 + mg\vec{Y}_f$$

$$v_i = \sqrt{v_f^2 + 2g\vec{Y}_f - 2g\vec{Y}_i} = ((5.00)^2 + 2(9.80)(16.0 - 2.00))^{1/2}$$

$$v_i = 17.3 \text{ m/s}$$

38) With two springs, the elastic potential energy is twice as big as it was with only one spring.

$$\frac{2U_s}{U_s} = \frac{\frac{1}{2}mv^2}{\frac{1}{2}mv_0^2} \quad \frac{v^2}{v_0^2} = 2 \quad v = \sqrt{2}v_0$$

39) With two springs, each spring is compressed only half the distance.

$$\text{Two springs: } U_s = 2\left(\frac{1}{2}k\left(\frac{\Delta x}{2}\right)^2\right) = \frac{1}{4}k(\Delta x)^2 = \frac{1}{2}\left(\frac{1}{2}k(\Delta x)^2\right)$$

With two springs, the elastic potential energy is half as big as it was with only one spring.

$$\frac{\frac{1}{2}U_s}{U_s} = \frac{\frac{1}{2}mv^2}{\frac{1}{2}mv_0^2} \quad \frac{v^2}{v_0^2} = \frac{1}{2} \quad v = \frac{v_0}{\sqrt{2}}$$

$$40) (a) \vec{v}_{iB} = -\sqrt{2gh} = -(2(9.80)(10.0))^{1/2} \quad \vec{v}_{ie} = 0$$

$$\vec{v}_{fB} = +\sqrt{2gh} = +(2(9.80)(10.0))^{1/2} \quad \vec{v}_{fe} = ?$$

Conservation of Momentum: $m_B \vec{v}_{iB} + m_e \vec{v}_{ie} = m_B \vec{v}_{fB} + m_e \vec{v}_{fe}$

$$\vec{v}_{fe} = \frac{m_B \vec{v}_{iB} - m_B \vec{v}_{fB}}{m_e} = \frac{m_B (-\sqrt{2gh} - \sqrt{2gh})}{m_e}$$

$$\vec{v}_{fe} = \frac{-2m_B \sqrt{2gh}}{m_e} = \frac{-(2)(0.500)(2(9.80)(10.0))^{1/2}}{(5.98 \times 10^{24})}$$

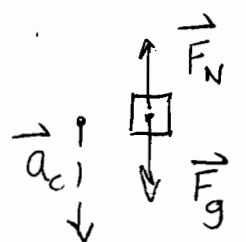
$$\vec{v}_{fe} = -2.34 \times 10^{-24} \text{ m/s}$$

$$(b) v = \frac{\Delta y}{\Delta t} \quad \Delta t = \frac{\Delta y}{v} = \frac{(1.00 \times 10^{-3})}{(2.34 \times 10^{-24})} = 4.2714 \times 10^{20} \text{ s}$$

$$\Delta t = 4.2714 \times 10^{20} \text{ s} \frac{1}{(86400 \text{ s/day})(365.25 \text{ day/yr})}$$

$$\Delta t = 1.35 \times 10^{13} \text{ years}$$

53) (a) Find the maximum speed first, which will occur when the object continues to move in a circle and the normal force approaches zero.



$$\sum \vec{F}_y = F_N - F_g = -ma_c \quad 0 - F_g = -ma_c$$

$$F_g = ma_c \quad mg = m \frac{v^2}{R} \quad v^2 = gR \quad v = \sqrt{gR}$$

$$h_{\max} = ? \quad K_i + U_{gi} = K_f + U_{gf}$$

$$0 + mgh = \frac{1}{2}mv^2 + mgR \quad mgh = \frac{1}{2}mgR + mgR$$

$$h = \frac{1}{2}R + R \quad h_{\max} = \frac{3}{2}R$$

$$(b) h_{\max} = \frac{3}{2}(10.0) = 15.0 \text{ m}$$

60) (a) The nitrogen atom is either above or below the xy -plane containing the three hydrogen atoms. It oscillates back and forth about its equilibrium position.

(b) With a total energy greater than the potential energy at $z=0$, the nitrogen atom has enough energy to oscillate about $z=0$, back and forth (or up and down) across the xy -plane.

61) Equilibrium $F_x = \frac{dU}{dx} = 0$ min = stable max = unstable

$$(a) \frac{dU}{dx} = 1 + 2\cos 2x = 0 \quad 2\cos 2x = -1 \quad \cos 2x = -\frac{1}{2}$$

$$2x = \cos^{-1}\left(-\frac{1}{2}\right) = \frac{2\pi}{3} \text{ rad}, \frac{4\pi}{3} \text{ rad} \quad x = \frac{\pi}{3} \text{ rad}, \frac{2\pi}{3} \text{ rad}$$

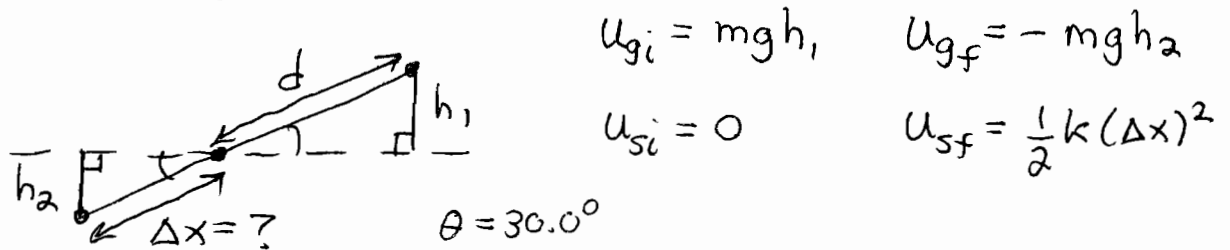
$$(b) \frac{d^2U}{dx^2} = -4\sin 2x \quad \frac{d^2U}{dx^2} \left(x = \frac{\pi}{3} \text{ rad}\right) = -4\sin \frac{2\pi}{3} = -2\sqrt{3}$$

$$\frac{d^2U}{dx^2} \left(x = \frac{\pi}{3} \text{ rad}\right) < 0 \quad \text{max} = \text{unstable}$$

$$\frac{d^2U}{dx^2} \left(x = \frac{2\pi}{3} \text{ rad}\right) = -4\sin \frac{4\pi}{3} = +2\sqrt{3} > 0 \quad \text{min} = \text{stable}$$

71) $m = 10.0 \text{ kg}$ $d = 4.00 \text{ m}$ $k = 250 \text{ N/m}$

(a) At maximum compression, the speed is zero. The initial speed is also zero.



$$U_{gi} = mgh_1 \quad U_{gf} = -mgh_2$$

$$U_{si} = 0$$

$$U_{sf} = \frac{1}{2}k(\Delta x)^2$$

$$K_i + U_{gi} + U_{si} = K_f + U_{gf} + U_{sf}$$

$$0 + mgh_1 + 0 = 0 - mgh_2 + \frac{1}{2}k(\Delta x)^2$$

$$\sin 30^\circ = \frac{h_2}{\Delta x} \quad h_2 = \Delta x \sin 30^\circ = \frac{\Delta x}{2}$$

$$\sin 30^\circ = \frac{h_1}{d} \quad h_1 = d \sin 30^\circ = \frac{d}{2}$$

$$mg \frac{d}{2} = -mg \frac{\Delta x}{2} + \frac{1}{2}k(\Delta x)^2$$

$$k(\Delta x)^2 - mg \Delta x - mgd = 0$$

$$\Delta x = \frac{-(-mg) \pm \sqrt{(-mg)^2 - 4k(-mgd)}}{2k} = \frac{mg \pm \sqrt{(mg)^2 + 4kmgd}}{2k}$$

Since $\Delta x > 0$, must use plus sign.

$$\Delta x = \frac{(10.0)(9.80) + \left((10.0)(9.80)^2 + (4)(250)(10.0)(9.80)(4.00) \right)^{1/2}}{(2)(250)}$$

$$\Delta x = \frac{98 + 633.72}{500} = 1.46 \text{ m}$$

$$(b) K_i + U_{gi} + U_{si} = K_f + U_{gf} + U_{sf}$$

$$0 + mg \frac{d}{2} + 0 = K_f - mg \frac{\Delta x}{2} + \frac{1}{2} k (\Delta x)^2$$

$$K_f = -\frac{1}{2} k (\Delta x)^2 + mg \frac{\Delta x}{2} + mg \frac{d}{2}$$

Maximum speed equates to maximum kinetic energy.

$$\frac{dK_f}{d\Delta x} = -k\Delta x + \frac{mg}{2} + 0 = 0 \quad k\Delta x = \frac{mg}{2}$$

$$\Delta x = \frac{mg}{2k} = \frac{(10.0)(9.80)}{(2)(250)} = 0.196 \text{ m} = 19.6 \text{ cm}$$